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sample.c

// NeoPixel Ring simple sketch (c) 2013 Shae Erisson
// released under the GPLv3 license to match the rest of the AdaFruit NeoPixel library

#include <Adafruit_NeoPixel.h>
#ifdef __AVR__
#include <avr/power.h>
#endif

// #define ANALOGMODE

// Which pin on the Arduino is connected to the NeoPixels?
// On a Trinket or Gemma we suggest changing this to 1
#define PIN 0

// How many NeoPixels are attached to the Arduino?
#define NUMPIXELS 1
// Modul State
#define IDLE_MODE 1
#define MOVE_MODE 2
#define REVERSE_MODE 3
#define MAX_POWER 254

// When we setup the NeoPixel library, we tell it how many pixels, and which pin to use to send signals.
// Note that for older NeoPixel strips you might need to change the third parameter--see the strandtest
// example for more information on possible values.
Adafruit_NeoPixel pixels = Adafruit_NeoPixel(NUMPIXELS, PIN, NEO_GRB + NEO_KHZ800);

int delayval = 5; // delay for half a second
#ifdef ANALOGMODE
int SenserPin = 2;
# else
int SenserPin = 4;
#endif
int RightPin = 1;
int LeftPin = 3;

void openDrainOut(int pin_no, int value)
{
  if(value== HIGH) {
    //入力にする
    pinMode(pin_no, INPUT_PULLUP);
  }
  else {
    pinMode(pin_no, OUTPUT);
    digitalWrite(pin_no, LOW);
  }
}

void setup() {
  // This is for Trinket 5V 16MHz, you can remove these three lines if you are not using a Trinket
#ifdef __AVR_ATtiny85__
  if (F_CPU == 8000000) clock_prescale_set(clock_div_1);
#endif
  // End of trinket special code
  pinMode(SenserPin, INPUT_PULLUP); // sets the digital pin as output

  pinMode(RightPin, INPUT_PULLUP);
  pinMode(LeftPin, INPUT_PULLUP);

  pixels.begin(); // This initializes the NeoPixel library.
}

void loop() {
  unsigned int r,g,b;
  int state;
  int sub_mode;
  int start_device;
  // For a set of NeoPixels the first NeoPixel is 0, second is 1, all the way up to the count of pixels minus one.
  r =0;
  g =0;
  b =0;
  delay(100);

  pixels.setPixelColor(0, pixels.Color(r,g,b)); // Moderately bright green color.

  pixels.show(); // This sends the updated pixel color to the hardware.

  delay(100);
}

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sub_mode =0;
start_device =0;
state = IDLE_MODE;
for(;;){
    switch(state){
        case IDLE_MODE:
//      pixels.setPixelColor(0, pixels.Color(r,0,0)); // Moderately bright green color.
//      pixels.show(); // This sends the updated pixel color to the hardware.
        if( sub_mode ==0){
            b++;
            if(b >= MAX_POWER){
                sub_mode =1;
            }
        }
        else {
            b --;
//          g++;
            if( b ==0){
                sub_mode =0;
            }
        }
        break;
        case MOVE_MODE:
        if(sub_mode == 0){
            b = MAX_POWER;
            g =0;
            r =0;
//          pixels.setPixelColor(0, pixels.Color(r,g,b)); // Moderately bright green color.
//          pixels.show(); // This sends the updated pixel color to the hardware.
            sub_mode =1;
        }
        else if(sub_mode == 1){
            b--;
            r++;
            if(r == (MAX_POWER/2)){
                //ここで ioをドライブする
                if(start_device == SenserPin){
                    openDrainOut(LeftPin,LOW);
                    openDrainOut(RightPin,LOW);
                }
                else if(start_device== RightPin){
                    openDrainOut(LeftPin,LOW);
                }
                else {
                    openDrainOut(RightPin,LOW);
                }
            }

            if(r == MAX_POWER){
                sub_mode =2;
            }
        }
        else if(sub_mode == 2){
            r--;
            g++;
            if(g == MAX_POWER){
                sub_mode = 3;
            }
        }
        else if(sub_mode == 3){
            //なにもしない
        }
        break;
        case REVERSE_MODE:
        if(sub_mode == 3 || sub_mode == 2){ // 緑から変化
            if(g >r){
                if(g >0){
                    g--;
                }
            }
            if(r > 0){
                r--;
            }
        }
        if(b != MAX_POWER){
            b++;
        }
        if(g == (MAX_POWER/2)){
            //ここで ioをドライブする
            openDrainOut(LeftPin,HIGH);
            openDrainOut(RightPin,HIGH);
        }
    }
}
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    }
    if(g == 0){
        sub_mode =1;
        state = IDLE_MODE;
    }
}
else if(r >= g){
    if(r >0){
        r--;
    }
    if(g != 0){
        g--;
    }
    if(b != MAX_POWER){
        b++;
    }
    if(r ==0){
        sub_mode =1;
        //ここで ioをドライブする
        openDrainOut(LeftPin, HIGH);
        openDrainOut(RightPin, HIGH);
        state = IDLE_MODE;
    }
}
}
else if(sub_mode == 1){ // から変化
    if ( r > 0){
        r--;
    }
    b++;
    if(r ==0){
        sub_mode =0;
        //ここで ioをドライブする
        openDrainOut(LeftPin, HIGH);
        openDrainOut(RightPin, HIGH);
        state = IDLE_MODE;
    }
}
}

break;
}
// センサー状態確認
#ifdef ANALOGMODE
if(analogRead(SensorPin)<=100){ //さわられた
# else
if(digitalRead(SensorPin)==0){ //さわられた
# endif
    if(state == IDLE_MODE){
        state = MOVE_MODE;
        sub_mode =0;
        start_device = SensorPin;
    }
}
#ifdef ANALOGMODE
else if(analogRead(SensorPin)>=900){ //はなされた
# else
else if(digitalRead(SensorPin)==1){ //はなされた
# endif
    if(state ==MOVE_MODE){
        if(start_device == SensorPin){
            state = REVERSE_MODE;

        }
        else if(start_device == RightPin){
            if(digitalRead(RightPin)==HIGH){
                state = REVERSE_MODE;
            }
        }
        else {
            if(digitalRead(LeftPin)==HIGH){
                state = REVERSE_MODE;
            }
        }
    }
}
else if(state ==IDLE_MODE){
    if(digitalRead(RightPin)==LOW){
        state = MOVE_MODE;
        sub_mode =0;
        start_device = RightPin;
    }
}
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        else if(digitalRead(LeftPin)==LOW) {
            state = MOVE_MODE;
            sub_mode =0;
            start_device = LeftPin;
        }
    }
}
// pixels.Color takes RGB values, from 0,0,0 up to 255,255,255
pixels.setPixelColor(0, pixels.Color(r,g,b)); // Moderately bright green color.
pixels.show(); // This sends the updated pixel color to the hardware.

if(state ==IDLE_MODE) {
    delayval = 5;
}
else {
    delayval = 3;
}
delay(delayval); // Delay for a period of time (in milliseconds).
// pixels.setPixelColor(0, pixels.Color(0,0,0)); // Moderately bright green color.
// pixels.show(); // This sends the updated pixel color to the hardware.

// delay(1); // Delay for a period of time (in milliseconds).

}
}
```